## 805.

## NOTE ON ABEL'S THEOREM.

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Considering Abel's theorem in so far as it relates to the first kind of integrals, and as a differential instead of an integral theorem, the theorem may be stated as follows:

We have a fixed curve f(x, y, 1) = 0 of the order m; this implies a relation f'(x) dx + f'(y) dy = 0, between the differentials dx, dy of the coordinates of a point on the curve; and we may therefore write

$$d\omega = \frac{dx}{f'(y)} = -\frac{dy}{f'(x)},$$

and, instead of dx or dy, use  $d\omega$  to denote the displacement of a point (x, y) on the curve.

Taking for greater simplicity the fixed curve to be a curve without nodes or cusps, and therefore of the deficiency  $\frac{1}{2}(m-1)(m-2)$ , we consider its mn intersections by a variable curve  $\phi(x, y, 1) = 0$  of the order n. And then, if  $(x, y, 1)^{m-3}$  denote an arbitrary rational and integral function of (x, y) of the order m-3, the theorem is that we have between the displacements  $d\omega_1, d\omega_2, \ldots, d\omega_{mn}$  of the mn points of intersection, the relation

$$\Sigma (x, y, 1)^{m-3} d\omega = 0,$$

where the left-hand side is the sum of the values of  $(x, y, 1)^{m-3} d\omega$ , belonging to the mn points of intersection respectively.

For the proof, observe that, varying in any manner the curve  $\phi$ , we obtain

$$\frac{d\phi}{dx}\,dx + \frac{d\phi}{dy}\,dy + \delta\phi = 0,$$

where  $\delta \phi$  is that part which depends on the variation of the coefficients, of the whole variation of  $\phi$ ; viz. if  $\phi = ax^n + bx^{n-1}y + ...$ , then  $\delta \phi = x^n da + x^{n-1}y db + ...$ ;  $\delta \phi$  is thus, in regard to the coordinates (x, y), a rational and integral function of the order n. Writing in this equation

$$dx$$
,  $dy = \frac{df}{dy} d\omega$ ,  $-\frac{df}{dx} d\omega$ ,

the equation becomes

$$\left(\frac{d\phi}{dx}\frac{df}{dy} - \frac{d\phi}{dy}\frac{df}{dx}\right)d\omega + \delta\phi = 0,$$

or say

$$-J(f, \phi) d\omega + \delta\phi = 0,$$

that is,

$$d\omega = \frac{\delta\phi}{J(f, \phi)};$$

and then multiplying each side by the arbitrary function  $(x, y, 1)^{m-3}$ , we have

$$\Sigma (x, y, 1)^{m-3} d\omega = \Sigma \frac{(x, y, 1)^{m-3}}{J(f, \phi)} \delta \phi,$$

where  $\delta \phi$  being of the order n in the variables, the numerator is a rational and integral function of (x, y) of the order m+n-3: hence by a theorem contained in Jacobi's paper "Theoremata nova algebraica circa systema duarum æquationum inter duas variabiles," *Crelle*, t. XIV. (1835), pp. 281—288, [Ges. Werke, t. III., pp. 285—294], the sum on the right-hand side is = 0: hence the required result  $\Sigma(x, y, 1)^{m-3} d\omega = 0$ .

Observing that  $(x, y, 1)^{m-3}$  is an arbitrary function, the equation just obtained breaks up into the equations

$$\sum d\omega = 0$$
,  $\sum x d\omega = 0$ ,  $\sum y d\omega = 0$ ,...,  $\sum x^{m-3} d\omega = 0$ ,...,  $\sum y^{m-3} d\omega = 0$ ,

viz. the number of equations is

$$1+2+\ldots+(m-2), = \frac{1}{2}(m-1)(m-2),$$

which is =p, the deficiency of the curve.

Suppose the fixed curve f(x, y, 1) = 0 is a cubic, m = 3, and we have the single relation  $\sum d\omega = 0$ , where the summation refers to the 3n points of intersection of the cubic and of the variable curve of the order n,  $\phi(x, y, 1) = 0$ .

In particular, if this curve be a line, n=1, and the equation is  $d\omega_1 + d\omega_2 + d\omega_3 = 0$ ; here the two points  $(x_1, y_1)$ ,  $(x_2, y_2)$  taken at pleasure on the cubic, determine the line, and they consequently determine uniquely the third point of intersection  $(x_3, y_3)$ ; there should thus be a single equation giving the displacement  $d\omega_3$  in terms of the displacements  $d\omega_1$ ,  $d\omega_2$ ; viz. this is the equation just found

$$d\omega_1 + d\omega_2 + d\omega_3 = 0.$$

So if the variable curve be a conic, n=2; and we have between the displacements of the six points the relation

$$d\omega_1 + d\omega_2 + \ldots + d\omega_6 = 0:$$

here five of the points determine the conic, and they therefore determine uniquely the sixth point; and there should be between the displacements a single relation as just found.

If the variable curve be a cubic, n=3, and we have between the displacements of the nine points the relation

$$d\omega_1 + d\omega_2 + \ldots + d\omega_9 = 0$$
:

here eight of the points do not determine the cubic  $\phi$ , but they nevertheless determine the ninth point, viz. (reproducing the reasoning which establishes this well-known and fundamental theorem as to cubic curves) if  $\phi_0 = 0$  be a particular cubic through the 8 points, then the general cubic is  $\phi_0 + kf = 0$ , and the intersections with f = 0 are given by the equations  $\phi_0 = 0$ , f = 0; whence the ninth point is independent of k, and is determined uniquely by the 8 points. There should thus be a single relation between the displacements, viz. this is the relation just found.

And so if the variable curve be a quartic, or curve of any higher order, it appears in like manner that there should be a single relation between the displacements; this relation being in fact the foregoing relation  $\Sigma d\omega = 0$ .

But take the fixed curve to be a quartic, m=4: then we have between the displacements  $d\omega$  the relation

$$\sum (x, y, 1) d\omega = 0$$
,

that is, the three equations

$$\sum x d\omega = 0$$
,  $\sum y d\omega = 0$ ,  $\sum d\omega = 0$ .

If the variable curve is a conic, n=2, then there are 8 points of intersection; 5 of these taken at pleasure determine the conic, and they consequently determine the remaining 3 points of intersection: hence there should be 3 equations. And so if the variable curve be a curve of any higher order, then by considerations similar to those made use of in the case where the first curve is a cubic it appears that the number of equations between the displacements  $d\omega$  should always be =3.

But if the variable curve be a line, n=1, then the number of the points of intersection is =4:2 of these taken at pleasure determine the line, and they consequently determine the remaining 2 points of intersection; and the number of equations between the displacements  $d\omega$  should thus be =2. But by what precedes, we have the 3 equations

$$d\omega_1 + d\omega_2 + d\omega_3 + d\omega_4 = 0,$$
  
 $x_1 d\omega_1 + x_2 d\omega_2 + x_3 d\omega_3 + x_4 d\omega_4 = 0,$   
 $y_1 d\omega_1 + y_2 d\omega_2 + y_3 d\omega_3 + y_4 d\omega_4 = 0;$ 

here the 4 points of intersection are on a line y = ax + b; we have therefore  $y_1 = ax_1 + b$ , ...,  $y_4 = ax_4 + b$ ; the equations between the  $d\omega$ 's give

$$(y_1 - ax_1 - b) d\omega_1 + ... + (y_4 - ax_4 - b) d\omega_4 = 0,$$

that is, is a single relation 0=0; or the 3 equations thus reduce themselves to 2 independent equations.

Again, if the fixed curve be a quintic, m = 5, there are here between the displacements the 6 equations

$$\sum x^2 d\omega = 0$$
,  $\sum xy d\omega = 0$ ,  $\sum y^2 d\omega = 0$ ,  
 $\sum x d\omega = 0$ ,  $\sum y d\omega = 0$ ,  $\sum d\omega = 0$ ;

the two cases in which the number of independent equations is less than 6 are (i) when the variable curve is a line, and (ii) when the variable curve is a conic. For the line n=1, and the number should be =3. We have the above 6 equations; but the equation of the line is ax+by+c=0, that is, we have  $ax_1+by_1+c=0$ , &c.; we deduce the 3 identical equations

$$\sum x(ax+by+c)=0$$
,  $\sum y(ax+by+c)=0$ ,  $\sum (ax+by+c)=0$ ,

and the number of independent equations is thus 6-3, = 3 as it should be.

So when the variable curve is a conic, n=2; the number of independent equations should be =5. The points of intersection lie on a conic  $(a, b, c, f, g, h)(x, y, 1)^2 = 0$ ; we have therefore the several equations  $(a, b, c, f, g, h)(x_1, y_1, 1)^2 = 0$ , &c.: we have therefore the single identical equation

$$\Sigma(a, b, c, f, g, h)(x, y, 1)^2 d\omega = 0,$$

and the number of independent equations is 6-1, = 5 as it should be.

Obviously the like considerations apply to the case where the fixed curve is a curve of any given order whatever.