

Recent Advances in Fuzzy Sets, Intuitionistic Fuzzy Sets, Generalized Nets and Related Topics Volume II: Applications

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**Systems Research Institute
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Structure of a lip-reading system based on IF-Sets

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Abstract

This paper presents the structure of a lip reading system. A method of encoding lip shapes is presented and a similarity/dissimilarity measure, based on IF-Sets, for comparison of lip shapes in a recognition process is proposed. The use of IF-Sets methodology makes it possible to compare various lip shapes in a bipolar way involving both similarities and dissimilarities. It also allows the estimation of a hesitation degree for lip similarity, which expresses ignorance in comparing them.

Keywords: Atanassov IF-Sets, lip reading, lip shape encoding and comparison, similarity/dissimilarity measure.

1 Introduction

Recognizing and comparing lip shapes is very important for applications in audio-visual speech recognition (cf. [12], [13]), lip reading (cf. [6], [9]) and phonetics research (cf. [8]). This article presents an outline of a project which deals with visual speech recognition based on the movements of the lips.

An initial version was implemented to check establish whether speech recognition from the movement of the lips can be achieved using a computer. In this system we assumed that we would not be translating from video to an orthographical record of the text, but only converting into merged audio, human would assess for comprehensibility.

Recent Advances in Fuzzy Sets, Intuitionistic Fuzzy Sets, Generalized Nets and Related Topics. Volume II: Applications (K.T. Atanassov, W. Homenda, O. Hryniewicz, J. Kacprzyk, M. Krawczak, Z. Nahorski, E. Szmidt, S. Zadrożny, Eds.), IBS PAN - SRI PAS, Warsaw, 2010.

The system consists of three main processes: Learning, Recognizing and Encoding. The recognizing and learning processes use the encoding process to extract numerical representations from frames of video input. The encoding process consists of a face detection module and lip-shape detection and encoding. In the learning process a knowledge base is built up. This means that groups of video frames with encoded lip-shapes are associated with their interpretations – recorded sounds. In the recognition process similarity measures are used to find best fitting lip-shapes representations and reproduce associated audio records. Figure 1 shows a schematic diagram of the entire lip-reading system.

We will present concepts relating to the numerical modelling of lip shapes and their comparison, employing the idea of IF-Sets. Using such concepts it is possible to compare lip shapes in a bipolar view. We can see how two lip shapes are similar to each other and simultaneously how they are dissimilar. We can also estimate our hesitation degree for lip similarity which expresses our ignorance in comparing them.

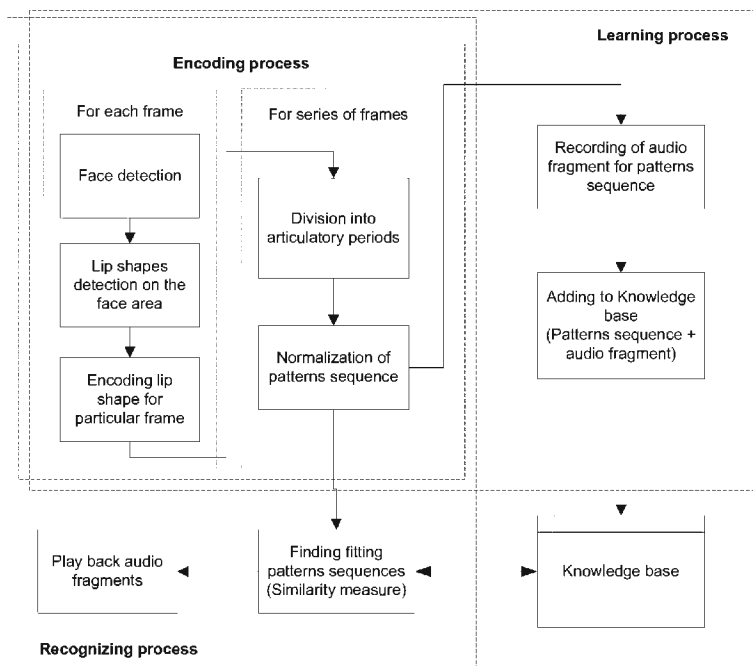


Figure 1: Architecture of the lip-reading system

2 Preliminaries

The notion of intuitionistic fuzzy sets (IF-Sets) was introduced by Atanassov in 1986 ([1]). It can be viewed as a generalization of fuzzy sets as introduced by Zadeh in 1965 ([16]). They deliver tools for modelling simultaneously positive and negative information approaches to different phenomena and enable us to estimate our level of ignorance about them.

Definition 1 *An intuitionistic fuzzy set (IF-Set) A in the universe X is an object of the form $A = \{\langle x; \mu(x); \nu(x) \rangle : x \in X\}$ where μ and ν are degrees of membership and non-membership of each $x \in X$, respectively, and $0 \leq \mu(x) + \nu(x) \leq 1$ for each $x \in X$.*

The number $\pi_A(x) = 1 - \mu_A(x) - \nu_A(x)$ is called the hesitation margin (or intuitionistic fuzzy index) of the IF-Set A .

More details on the theory of Atanassov intuitionistic fuzzy sets can be found in [1], [2], [7], [11] and [14, 15].

Very interesting applications of IF-Sets for image processing and pattern recognition can be found in [3], [5] and [4].

3 The lip shape encoding

The main task in the process of building a lip shape model is to construct an encoded pattern of a given lip shape, that is representative and easy to compute and compare. The whole process is performed in an automatic manner. We used the OpenCV library (see [10]) which provided the necessary machineries of image processing for the implementation.

The procedure of lip shape pattern encoding is as follows.

In the first step, on the picture of the face we mark two points denoting the lip corners, which are denoted by c_1 and c_5 . The segment linking the two points is divided into four parts limited by points c_2, c_3, c_4 through which segments parallel to the segment c_1, c_5 are drawn limited by the edges of the lips, setting test points u_1, u_2 for the upper lips and l_1, l_2, l_3 for the lower lips. In this manner a pattern for the lip arrangement is constructed (see Fig. 2).

In order to make this model independent of different sizes of lips or of the picture the ratios of the lengths of vertical and horizontal segments are encoded in the pattern, rather than the distances between individual marked points. (see Fig. 3).

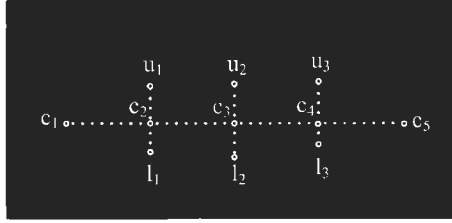


Figure 2: Control points on the lip shape

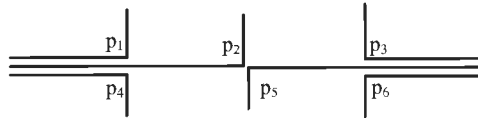


Figure 3: Coding pattern of the lip shape

Definition 2 Lip pattern P is defined as the vector:

$$P = (p_1, p_2, p_3, p_4, p_5, p_6) \text{ where } p_i \in [0, 1] \text{ and } p_1 = \frac{|u_1, c_2|}{|c_1, c_2|}, p_2 = \frac{|u_2, c_3|}{|c_1, c_3|}, p_3 = \frac{|u_3, c_4|}{|c_4, c_5|}, p_4 = \frac{|l_1, c_2|}{|c_1, c_2|}, p_5 = \frac{|l_2, c_3|}{|c_1, c_3|}, p_6 = \frac{|l_3, c_4|}{|c_4, c_5|}.$$

Here p_i will be called the i -th pattern part of P .

It should be emphasized that an individual element of the lip shape pattern p_i takes values from the period $[0, 1]$, and if p_i is closer to 1 then the vertical and horizontal distances are more equal. If $p_i = 0$ then there is no vertical deviation from the line connecting the lip corners.

4 The lip movements - division into articulatory periods

The proper division of continuous video input into informative periods is an important component of the system. Not only lip shapes, but also their changes in a time, are essential. The input video consists of frames. Every frame is described by the system with a given lip pattern. We obtain a conversion of the video into a sequence of numeric data. Then this data should be grouped into minimal informational sequences which will constitute the knowledge base. In performing this process we assume that the sequence of lip patterns is formed only from monotonic items, i.e. the movement of the lips takes place vertically only in one established direction.

Finally, sequences of lip patterns prepared in this way are normalized and audio covering this sequence is recorded. They constitute pairs: articulatory periods – audio representation, which are added to the knowledge-base.

5 Similarity measure

The appropriate structure of the similarity measure is the next very important element of the system, playing a large role in the learning and recognition processes.

The construction of a lip shape similarity measure involves three steps:

1. calculation of a distance between particular pattern parts of two lip patterns;
2. interpretation of the distance by means of similarity and dissimilarity degree (constructing the IF-Set of each distance between corresponding pattern parts);
3. aggregation to one similarity and one dissimilarity measure value.

Definition 3 Let a_i, b_i be the i -th pattern parts of the lip patterns A, B respectively. The similarity degree $sim_i(A, B)$ of the i -th pattern parts is defined as $sim_i(A, B) = (1 - |a_i - b_i|)^2$ and the dissimilarity degree of the i -th pattern parts is defined as $dis_i(A, B) = |a_i - b_i|^2$.

Definition 4 Let A, B be lip patterns. The IFS-LIP measure $L(A, B)$ is a triple (SIM, DIS, HES) such as $L : A, B \rightarrow (SIM, DIS, HES)$ and

$$SIM(A, B) = \frac{\sum_{i=1}^6 (w_i * sim_i(A, B))}{\sum_{i=1}^6 w_i},$$

$$DIS(A, B) = \frac{\sum_{i=1}^6 (w_i * dis_i(A, B))}{\sum_{i=1}^6 w_i},$$

$$HES(A, B) = 1 - SIM(A, B) - DIS(A, B),$$

$\forall_{A,B} 0 \leq SIM(A, B) + DIS(A, B) \leq 1$ where w_i is the weight representing the importance of the i -th lip pattern.

As can be noticed, we have applied the weighted average of membership degrees as an aggregation operator. The selection of appropriate values of w_i is very important. If all w_i values are equal to 1, all fragments of the pattern will affect the measure in the same way. However experimental results have suggested that central elements of the lip pattern should have greater weights assigned. Therefore we suggest using the vector of weights $w = (1, 2, 1, 1, 2, 1)$.

6 Example

Table 1 presents four pictures of lip arrangements with the corresponding patterns.

Table 1: Lip shapes with encoded patterns $P_1 - P_4$


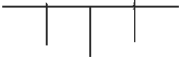






  $P_1 = (0.05, 0, 0.14, 0.89, 0.58, 0.78)$	  $P_2 = (0.15, 0.05, 0.12, 0.88, 0.54, 0.78)$
  $P_3 = (0.22, 0.05, 0.05, 0.73, 0.47, 0.51)$	  $P_4 = (0.13, 0, 0.03, 0.62, 0.44, 0.56)$

Table 2 presents values of the IFS-LIP measure between the lip arrangements in Table 1.

Table 2: Computed values of IFS-LIP measure

	p_1	p_2	p_3	p_4
p_1	(1,0,0)	(0.93,0,0.07)	(0.75,0.02,0.23)	(0.75,0.03,0.22)
p_2	(0.93,0,0.07)	(1,0,0)	(0.81,0.02,0.17)	(0.78,0.02,0.2)
p_3	(0.75,0.02,0.23)	(0.81,0.02,0.17)	(1,0,0)	(0.88,0,0.11)
p_4	(0.75,0.03,0.22)	(0.78,0.02,0.2)	(0.88,0,0.11)	(1,0,0)

After verification of the results, it can be concluded that the constructed measure provides a more compressive form of information about the relations between lip arrangements. Apart from the information about similarities between lip patterns (e.g. the relatively high similarity between p_1 and p_2 , p_6 and p_8) we additionally obtain essential information about hesitation in determining the power of

similarity (e.g. p_1 vs. p_6 and p_1 vs. p_8 where the hesitation margin is higher than the degree of similarity).

7 Summary

We have presented an overview of the lip-reading system on which we are currently working. The idea of encoding lip shapes into patterns and comparing such patterns to the suggested measure IFS-LIP appears to be very promising. We have attempted to utilize the approach suggested by Atanassov, which involves taking a dual view of the data. Our work presents the initial stage of more complex research on the modelling of lip shapes. The first results show that the applied solution can work in the process of automatic lip reading.

Acknowledgment

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The papers presented in this Volume 2 constitute a collection of contributions, both of a foundational and applied type, by both well-known experts and young researchers in various fields of broadly perceived intelligent systems.

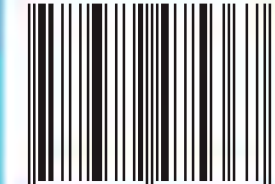
It may be viewed as a result of fruitful discussions held during the Ninth International Workshop on Intuitionistic Fuzzy Sets and Generalized Nets (IWIFSGN-2010) organized in Warsaw on October 8, 2010 by the Systems Research Institute, Polish Academy of Sciences, in Warsaw, Poland, Institute of Biophysics and Biomedical Engineering, Bulgarian Academy of Sciences in Sofia, Bulgaria, and WIT - Warsaw School of Information Technology in Warsaw, Poland, and co-organized by: the Matej Bel University, Banska Bystrica, Slovakia, Universidad Publica de Navarra, Pamplona, Spain, Universidade de Tras-Os-Montes e Alto Douro, Vila Real, Portugal, and the University of Westminster, Harrow, UK:

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The consecutive International Workshops on Intuitionistic Fuzzy Sets and Generalized Nets (IWIFSGNs) have been meant to provide a forum for the presentation of new results and for scientific discussion on new developments in foundations and applications of intuitionistic fuzzy sets and generalized nets pioneered by Professor Krassimir T. Atanassov. Other topics related to broadly perceived representation and processing of uncertain and imprecise information and intelligent systems have also been included. The Ninth International Workshop on Intuitionistic Fuzzy Sets and Generalized Nets (IWIFSGN-2010) is a continuation of this undertaking, and provides many new ideas and results in the areas concerned.

We hope that a collection of main contributions presented at the Workshop, completed with many papers by leading experts who have not been able to participate, will provide a source of much needed information on recent trends in the topics considered.

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