

617.

ON THE SCALENE TRANSFORMATION OF A PLANE CURVE.

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THE transformation by reciprocal radius vectors can be effected mechanically by Sylvester's Peaucellier-cell. But, employing a more general cell (considered incidentally by him) which may be called the scalene-cell, we have the scalene transformation in question*; viz. if, in two curves, r, r' are radius vectors belonging to the same angle (or say opposite angles) θ , then the relation between r, r' is

$$rr'(r+r')+(m^2-l^2)r+(m^2-n^2)r'=0;$$

or, as this may also be written,

$$r^2 + \left(r' - \frac{l^2 - m^2}{r'} \right) r + m^2 - n^2 = 0.$$

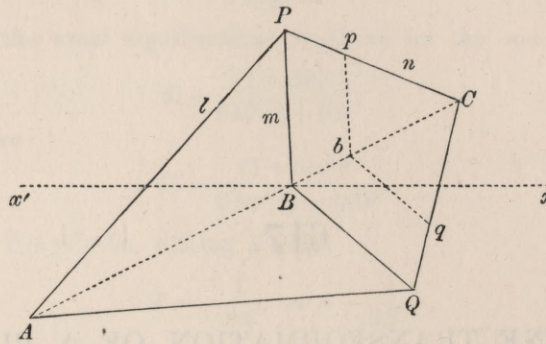
The transformation is, it will be seen, an interesting one for its own sake, independently of the remarkably simple mechanical construction, viz. the scalene cell is simply a system of 3 pairs of equal rods $PA, QA; PB, QB; PC, QC$ (fig. 1, p. 528), jointed together at and capable of rotating about the points P, Q, A, B, C ; the three lengths PA, PB, PC (say these are $=l, m, n$) are all of them unequal: in the case of any two of them equal, we have Peaucellier or isosceles cell. The effect of the arrangement is that the points A, B, C are retained in a right line, the distances $BA, =r'$, and $BC, =r$, being connected by the above-mentioned equation; so that taking B as a fixed point, if the point A describe any given curve, the point C will describe the corresponding or transformed curve.

In the case where the given curve is a right line or a circle, we may through B draw at right angles to the curve the axis $x'Bx$: viz. in the case of the circle,

* The transformation itself, and doubtless many of the results obtained by means of it, are familiar to Prof. Sylvester; and I abandon all claim to priority.

the axis $x'Bx$ passes through its centre; and we measure the angle θ from this line, viz. we write $\angle x'BC = \angle x'BA = \theta$.

Fig. 1.



Suppose, first, that the locus of A is a right line, or a circle passing through B . Its equation is $r' = \frac{c}{\cos \theta}$ or $= c \cos \theta$; and we accordingly have for the transformed curve

$$r^2 + \left(\frac{c}{\cos \theta} - \frac{l^2 - m^2}{c \cos \theta} \right) r + m^2 - n^2 = 0,$$

or else

$$r^2 + \left(c \cos \theta - \frac{l^2 - m^2}{c \cos \theta} \right) r + m^2 - n^2 = 0;$$

viz. multiplying in each case by $r \cos \theta$, and then writing $r \cos \theta = x$, $r^2 = x^2 + y^2$, the equations become

$$x(x^2 + y^2) + c(x^2 + y^2) - \frac{l^2 - m^2}{c} x^2 + (m^2 - n^2)x = 0,$$

and

$$x(x^2 + y^2) + cx^2 - \frac{l^2 - m^2}{c}(x^2 + y^2) + (m^2 - n^2)x = 0;$$

viz. in each case the curve is a circular cubic passing through the origin B and having an asymptote parallel to the axis of y . The curve is nodal, if $m = n$, viz. in this case the origin is a node: or if $c = \sqrt{l^2 - n^2} + \sqrt{m^2 - n^2}$.

Suppose next that the locus of A is a circle, centre at a distance $= \gamma$ along Bx' and radius $= h$: we have

$$r'^2 - 2\gamma r' \cos \theta + \gamma^2 - h^2 = 0,$$

viz. if

$$\gamma^2 - h^2 = -(l^2 - m^2),$$

or, what is the same thing,

$$h^2 + m^2 = \gamma^2 + l^2,$$

then we have

$$r' - \frac{l^2 - m^2}{r'} = 2\gamma \cos \theta,$$

and the transformed curve is

$$r^2 + 2\gamma r \cos \theta + m^2 - n^2 = 0,$$

or, as this may be written,

$$r^2 + 2\gamma r \cos \theta + \gamma^2 - f^2 = 0,$$

where $\gamma^2 - f^2 = m^2 - n^2$, that is, $f^2 + m^2 = \gamma^2 + n^2$; viz. this is a concentric circle radius f .

The theorem may be presented as follows. Consider two concentric circles, centre O and radii h, f respectively; take an arbitrary point B , distance $OB = \gamma$; and taking m arbitrary, determine l, n by the equations

$$l^2 = m^2 + h^2 - \gamma^2, \quad n^2 = m^2 + f^2 - \gamma^2;$$

then drawing through B an arbitrary line to meet the circles in A, C respectively; also describing a circle, centre B and radius $= m$; and through O drawing a line perpendicular to ABC to meet the last-mentioned circle in two points P, Q : for these points, the distances from the points A, B, C are $= l, m, n$ respectively.

To verify this, take O as the origin, OB for the axis of x , θ the inclination of ABC to this axis, $BA = r'$, $BC = r$; the coordinates of C, B, A are

$$\begin{array}{ccc} \gamma + r \cos \theta, & r \sin \theta, & \\ \gamma & , & 0 \\ \gamma + r' \cos \theta, & - r' \sin \theta, & \end{array}$$

whence, taking (x, y) for the coordinates of P (or Q), the equations to be verified are

$$\begin{aligned} (x - \gamma - r \cos \theta)^2 + (y - r \sin \theta)^2 &= n^2, \\ (x - \gamma)^2 + y^2 &= m^2, \\ (x - \gamma + r' \cos \theta)^2 + (y + r' \sin \theta)^2 &= l^2. \end{aligned}$$

By means of the second equation, the other two become

$$\begin{aligned} -2(x - \gamma)r \cos \theta - 2yr \sin \theta + r^2 &= n^2 - m^2, \\ 2(x - \gamma)r' \cos \theta + 2yr' \sin \theta + r'^2 &= l^2 - m^2; \end{aligned}$$

or, substituting for $n^2 - m^2, l^2 - m^2$ the values $f^2 - \gamma^2$ and $h^2 - \gamma^2$, the equations are

$$\begin{aligned} -2xr \cos \theta - 2yr \sin \theta + r^2 + 2\gamma r \cos \theta + \gamma^2 - f^2 &= 0, \\ 2xr' \cos \theta + 2yr' \sin \theta + r'^2 - 2\gamma r' \cos \theta + \gamma^2 - h^2 &= 0, \end{aligned}$$

viz. in virtue of the equations of the two circles, these reduce themselves each of them to

$$x \cos \theta + y \sin \theta = 0,$$

which equation, together with the second equation

$$(x - \gamma)^2 + y^2 = m^2,$$

determine (x, y) as above.

Reverting to the case where the locus of A is the circle

$$r'^2 - 2\gamma r' \cos \theta + \gamma^2 - h^2 = 0,$$

this gives

$$r' = \gamma \cos \theta + \sqrt{(h^2 - \gamma^2 \sin^2 \theta)},$$

$$\frac{1}{r'} = \frac{\gamma \cos \theta - \sqrt{(h^2 - \gamma^2 \sin^2 \theta)}}{\gamma^2 - h^2};$$

so that for the transformed curve we have

$$r^2 + r \left(1 - \frac{l^2 - m^2}{\gamma^2 - h^2}\right) \gamma \cos \theta + r \left(1 + \frac{l^2 - m^2}{\gamma^2 - h^2}\right) \sqrt{(h^2 - \gamma^2 \sin^2 \theta)} + m^2 - n^2 = 0.$$

Putting for shortness $\frac{l^2 - m^2}{\gamma^2 - h^2} = \lambda$, and for r , $r \cos \theta$, $r \sin \theta$, writing $\sqrt{(x^2 + y^2)}$, x , y respectively, this is

$$x^2 + y^2 + (1 - \lambda) \gamma x + (1 + \lambda) \sqrt{\{h^2(x^2 + y^2) - \gamma^2 y^2\}} + m^2 - n^2 = 0,$$

or, what is the same thing,

$$\{x^2 + y^2 + (1 - \lambda) \gamma x + m^2 - n^2\}^2 = (1 + \lambda)^2 \{h^2(x^2 + y^2) - \gamma^2 y^2\},$$

a bicircular quartic. In the case $\lambda = -1$, it reduces itself to the circle

$$x^2 + y^2 + 2\gamma x + m^2 - n^2 = 0$$

twice, which is the case considered above; and in the case $\lambda = 1$, or $l^2 + h^2 = m^2 + \gamma^2$, the equation is

$$(x^2 + y^2 + m^2 - n^2)^2 = 4 \{h^2(x^2 + y^2) - \gamma^2 y^2\},$$

so that the curve is symmetrical in regard to each axis. In the case $\gamma = 0$, the locus is a pair of concentric circles, centre B .

The equation

$$\{x^2 + y^2 + (1 - \lambda) \gamma x + m^2 - n^2\}^2 = (1 + \lambda)^2 \{h^2(x^2 + y^2) - \gamma^2 y^2\},$$

which contains the four constants λ , γ , h and $m^2 - n^2$, may be written in the form

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + ey^2,$$

(where the constants A , B , a , e are also arbitrary). This is, in fact, the equation of the general symmetrical bicircular quartic, referred to a properly-selected point on the axis as origin, viz. the origin is the centre of any one of the three involutions formed by the vertices (or points on the axis); say it is any one of the three involution-centres of the curve.

To show this, assume

$$(x - \alpha)(x - \beta)(x - \gamma)(x - \delta) = x^4 - px^3 + qx^2 - rx + s :$$

then, taking B arbitrary, the equation of the symmetrical bicircular quartic having for vertices the points $x = \alpha$, $x = \beta$, $x = \gamma$, $x = \delta$, is

$$(x^2 + y^2 - \frac{1}{2}px + B)^2 = (2B + \frac{1}{4}p^2 - q)x^2 + (r - pB)x + (-s + B^2);$$

in fact, this is the form of the general equation, and writing therein $y = 0$, it becomes $x^4 - px^3 + qx^2 - rx + s = 0$, that is, $(x - \alpha)(x - \beta)(x - \gamma)(x - \delta) = 0$. Hence, writing for convenience

$$A = -\frac{1}{2}p,$$

$$a = 2B + \frac{1}{4}p^2 - q,$$

$$b = r - pB,$$

$$c = -s + B^2,$$

the equation is

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + bx + c.$$

This may be written

$$(x^2 + y^2 + Ax + B + \theta)^2 = (a + 2\theta)x^2 + 2\theta y^2 + (b + 2\theta A)x + c + 2B\theta + \theta^2,$$

viz. assuming $\theta = -\frac{b}{2A}$ in order on the right-hand side to destroy the term in x , the equation is

$$\left(x^2 + y^2 + Ax + B - \frac{b}{2A}\right)^2 = \left(a - \frac{b}{A}\right)x^2 - \frac{b}{A}y^2 + \frac{1}{4A^2}(b^2 - 4ABb + 4A^2c),$$

which is of the form

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + ey^2 + f;$$

and if $f = 0$, that is, if $b^2 - 4ABb + 4A^2c = 0$, then it is of the required form

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + ey^2.$$

We have

$$\begin{aligned} b^2 - 4ABb + 4A^2c &= (r - pB)^2 + 2pB(r - pB) + p^2(-s + B^2) \\ &= r^2 - p^2s, \end{aligned}$$

or the required condition is $r^2 - p^2s = 0$. But we have

$$p^2s - r^2 = (\alpha\delta - \beta\gamma)(\beta\delta - \gamma\alpha)(\gamma\delta - \alpha\beta),$$

as is easily verified by writing

$$p = \delta + p_0, \quad q = \delta p_0 + q_0, \quad r = \delta q_0 + r_0, \quad s = \delta r_0,$$

where p_0 , q_0 , r_0 stand for

$$\alpha + \beta + \gamma, \quad \beta\gamma + \gamma\alpha + \alpha\beta, \quad \alpha\beta\gamma,$$

respectively. The required condition thus is

$$(\alpha\delta - \beta\gamma)(\beta\delta - \gamma\alpha)(\gamma\delta - \alpha\beta) = 0,$$

viz. the origin (that is, the fixed point B of the cell) must be at one of the three involution-centres.

Comparing the equation

$$\{x^2 + y^2 + (1 - \lambda)\gamma x + m^2 - n^2\}^2 = (1 + \lambda)^2 \{h^2(x^2 + y^2) - \gamma^2 y^2\}$$

with the equation

$$\{x^2 + y^2 + Ax + B\}^2 = ax^2 + ey^2,$$

we have

$$A = (1 - \lambda)\gamma,$$

$$B = m^2 - n^2,$$

$$a = (1 + \lambda)^2 h^2,$$

$$e = (1 + \lambda)^2 (h^2 - \gamma^2),$$

and thence $a - e = (1 + \lambda)^2 \gamma^2$. Consequently $\frac{a - e}{A^2} = \left(\frac{1 + \lambda}{1 - \lambda}\right)^2$, which gives λ : and then

$h^2 = \frac{a}{(1 + \lambda)^2}$, $\gamma^2 = \frac{a - e}{(1 + \lambda)^2}$, $m^2 - n^2 = B$; viz. we thus have the values of λ , h , γ and $m^2 - n^2$ for the description of a given curve $\{x^2 + y^2 + Ax + B\}^2 = ax^2 + ey^2$. In order that the description may be possible, a and $a - e$ must be each of them positive.

For the Cartesian a is $= e$, whence $1 + \lambda = 0$, and the equation becomes

$$(x^2 + y^2 + 2\gamma x + m^2 - n^2)^2 = 0,$$

which is a twice repeated circle; hence the Cartesian cannot be constructed by means of a cell as above.

To obtain a construction of the Cartesian, it may be remarked that, if a symmetrical bicircular quartic be inverted in regard to an axial focus, viz. if the focus be taken as the centre of inversion, we obtain a Cartesian. The axial foci of the curve

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + ey^2$$

are points on the axis, the abscissa $x = \theta$ being determined by the equation

$$e(\theta^2 + A\theta + B)^2 - a(\theta^2 - B)^2 - ae\theta^2 = 0.$$

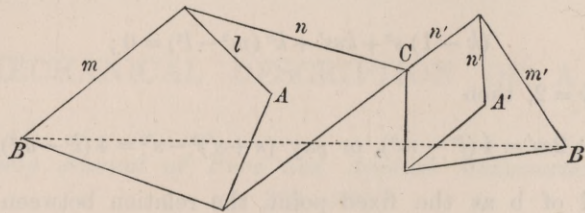
The equation referred to a focus as origin is therefore

$$\{x^2 + y^2 + (A + 2\theta)x + B + \theta^2\}^2 = ax^2 + ey^2 + 2a\theta x + \theta^2;$$

then inverting, viz. for x, y writing $\frac{k^2 x}{r^2}$, $\frac{k^2 y}{r^2}$ (k arbitrary), we have, as may be verified the equation of a Cartesian.

The inversion can be performed mechanically by an ordinary Peaucellier-cell; the complete apparatus for the construction of a Cartesian is therefore as in fig. 2, viz. we have a cell BAC as before, B a fixed point, locus of A a circle (for convenience of drawing, the arrangement has been made BAC instead of ABC), and we connect with C a Peaucellier-cell $CA'B'$, arms n', n', m' , the fixed point B' being on the axis, which is the line joining B with the centre of the circle described by A . This being so, then A describing a circle, C will describe a symmetrical bicircular quartic, and A' will describe the inverse of this, being in general a like curve; but if the position of B' be properly determined, viz. if B' be at a focus of the first-mentioned quartic,

Fig. 2.



then A' will describe a Cartesian. A further investigation would be necessary in order to determine how to adapt the apparatus to the description of a given Cartesian.

A more convenient mechanical description of a Cartesian is, however, that given in the paper which follows the present one [618].

The equation

$$\{x^2 + y^2 + (1 - \lambda) \gamma x + m^2 - n^2\}^2 = (1 + \lambda)^2 \{h^2 (x^2 + y^2) - \gamma^2 y^2\}$$

may also be written

$$\begin{aligned} & \{x^2 + y^2 + (1 - \lambda) \gamma x - \frac{1}{2} (1 + \lambda)^2 (h^2 - \gamma^2) + m^2 - n^2\}^2 \\ & = (1 + \lambda)^2 \{ \gamma^2 x^2 - (1 - \lambda) (h^2 - \gamma^2) \gamma x + \frac{1}{4} (1 + \lambda)^2 (h^2 - \gamma^2)^2 - (m^2 - n^2) (h^2 - \gamma^2) \}, \end{aligned}$$

viz. the equation is now brought into the form

$$(x^2 + y^2 + Ax + B)^2 = ax^2 + bx + c.$$

Expressing the coefficients A, B, a, b, c in terms of $\lambda, \gamma, h, m^2 - n^2$, it appears by what precedes, that we should have identically $b^2 - 4ABb + 4A^2c = 0$, viz. this is the equation which expresses that the origin is an involution-centre.

If, instead of the original cell, we consider a new cell obtained by substituting for the arms PB, BQ , the arms pb, bq , jointed on to the points p, q on the arms CP, CQ respectively, and instead of B , making b the fixed point; then writing $Cp = kn$, $pb = km$, so that the parameters of the cell are l, m, n, k , and taking $Cb = s, bA = s'$,

we have $s = kr$, $s + s' = r + r'$, that is, $r = \frac{s}{k}$, $r' = \frac{k-1}{k} s + s'$. Substituting in the equation between r , r' , written for greater convenience in the form

$$(r + r')(rr' + m^2 - l^2) + (l^2 - n^2)r' = 0,$$

the relation between s , s' is found to be

$$(s + s')\left(\frac{k-1}{k^2}s^2 + \frac{ss'}{k} + m^2 - l^2\right) + (l^2 - n^2)\left(\frac{k-1}{k}s + s'\right) = 0.$$

On account of the term in s^3 , this equation in its general form does not, it would appear, give rise to transformations of much elegance. If, however, $l = n$, then the relation becomes

$$(k-1)s^2 + kss' + k^2(m^2 - l^2) = 0;$$

and in particular, if $k = 2$, then

$$s^2 + 2ss' = 4(l^2 - m^2), \text{ or say } (s + s')^2 - s'^2 = 4(l^2 - m^2),$$

viz. taking A instead of b as the fixed point, the relation between the radii AC , Ab is $\rho^2 - \rho'^2 = 4(l^2 - m^2)$; the cell is in this case Sylvester's "quadratic-binomial extractor."