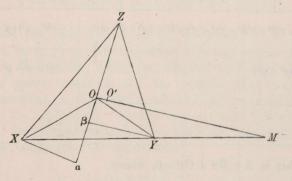
642.

ON A DIFFERENTIAL RELATION BETWEEN THE SIDES OF A QUADRANGLE.

[From the Messenger of Mathematics, vol. vi. (1877), pp. 99—101.]

LET the sides and diagonals YZ, ZX, XY, OX, OY, OZ of a quadrangle be f, g, h, a, b, c, and let the component triangles be denoted as follows:

$$A = \Delta Y Z O, = (b, c, f), \\ B = \Delta Z X O, = (c, a, g), \\ C = \Delta X Y O, = (a, b, h), \\ \Omega = \Delta X Y Z, = (f, g, h), \\$$



viz. A, B, C, Ω are the triangles whose sides are (b, c, f), (c, a, g), (a, b, h), (f, g, h) respectively, so that $\Omega = A + B + C$. Then we have between (a, b, c, f, g, h) an equation giving rise to a differential relation, which may be written

$$\Omega (Aada + Bbdb + Ccdc) - (BCfdf + CAgdg + ABhdh) = 0.$$

This may be proved geometrically and analytically. First, for the geometrical proof, it is enough to prove that, when a and b alone vary, the relation between the increments is Aada + Bbdb = 0; for then a and g alone varying, the relation between

C. X.

the increments will be $\Omega ada - Cgdg = 0$ (as to the negative sign it is clear from the figure that a, g will increase or diminish together): and we thence at once infer the general relation.

We have consequently to prove that, considering a and b as alone variable,

$$Aada + Bbdb = 0$$
;

or, what is the same thing,

$$ada: -bdb = XOZ: YOZ.$$

The points XYZ remain fixed; but O moves through the infinitesimal arc OO', centre Z, which may be considered as situate in the right line OM drawn from O at right angles to ZO, and meeting XY produced in the point M. And then, writing for a moment $\angle OXY = X$, $\angle OYX = Y$, $\angle OMY = M$, we find at once

$$da = OO' \cos (X + M),$$

-
$$db = OO' \cos (Y - M);$$

that is,

$$-\frac{da}{db} = \frac{\cos(X+M)}{\cos(Y-M)}, \text{ or } -\frac{ada}{bdb} = \frac{a\cos(X+M)}{b\cos(Y-M)}.$$

But drawing $X\alpha$, $Y\beta$ each of them at right angles to ZO, we have $a\cos(X+M)=X\alpha$, $b\cos(Y-M)=Y\beta$, and evidently $XOZ:YOZ=X\alpha:Y\beta$; whence the equation is $-\frac{ada}{bdb}=\frac{XOZ}{YOZ}$, which is the required relation.

For the analytical proof, it is to be observed that the relation between a, b, c, f, g, h is a quadric relation in the quantities a^2 , b^2 , c^2 , f^2 , g^2 , h^2 respectively; this may be written

say for a moment this is $A + Ba^2 + Ca^4 = 0$, where

$$\begin{split} A &= b^2 g^4 + b^4 g^2 + c^2 h^4 + c^4 h^2 \\ &- (b^2 + c^2) \ g^2 h^2 - (g^2 + h^2) \ b^2 c^2 \\ B &= - (b^2 - c^2) \ (g^2 - h^2) \\ C &= f^2 \,; \end{split}$$

then we have as usual

$$\frac{du}{d \cdot a^2} a da + \frac{du}{d \cdot b^2} b db + \&c. = 0,$$

where

$$\frac{1}{2} \frac{du}{d \cdot a^2} = Ca^2 + \frac{1}{2}B.$$

But in virtue of u = 0, we have

$$(Ca^2 + \frac{1}{2}B)^2 = C(Ca^4 + Ba^2 + A) + \frac{1}{4}(B^2 - AC),$$

that is, $\frac{du}{d \cdot a^2} = \sqrt{(B^2 - 4AC)}$; and here $B^2 - 4AC$ is a quartic function of f^2 , which is easily seen to reduce itself to the form

$$f^2 - (g+h)^2 f^2 - (g-h)^2 f^2 - (b+c)^2 f^2 - (b-c)^2$$
.

The coefficients of bdb, cdc, &c., are given as expressions of the like form; substituting their values, the differential relation is

$$\sqrt{\{f^2 - (g+h)^2 f^2 - (g-h)^2 f^2 - (b+c)^2 f^2 - (b-c)^2\}} ada + \&c. = 0,$$

which is, in fact, the foregoing result.

It is right to notice that there are in all 16 linear factors,

and this being so, the coefficients of ada, bdb, cdc, fdf, gdg, hdh, are

$$\sqrt{(dd'd''d''' \cdot ff'f''f''')}, -\sqrt{(gg'g''g''' \cdot hh'h''h''')},
\sqrt{(dd'd''d''' \cdot gg'g''g''')}, -\sqrt{(hh'h''h''' \cdot ff'f''f''')},
\sqrt{(dd'd''d''' \cdot hh'h''h''')}, -\sqrt{(ff'f''f''' \cdot gg'g''g''')},$$

respectively.

We may imagine the quadrilateral ZOXY composed of the four rods ZO, OX, XY, YZ (lengths c, a, h, f as before) jointed together at the angles, and kept in equilibrium by forces B, G acting along the diagonals OY(=b), ZX(=a) respectively. We have c, a, h, f given constants, and the relation $\phi(a, b, c, f, g, h) = 0$, which connects the six quantities is the relation between the two variable diagonals (g, b); by what precedes, the differential relation $\phi(a, b, c, f, g, h) = 0$ is equivalent to $\Omega Bbdb - CAgdg = 0$. By virtual velocities we have as the condition of equilibrium Bdb + Gdg = 0; hence, eliminating db, dg we have

$$\frac{B}{\Omega Bb} = -\frac{G}{CAg};$$

or, say

$$\frac{B}{b}: -\frac{G}{g} = \frac{1}{\Delta XYO \cdot \Delta ZYO}: \frac{1}{\Delta XYZ \cdot \Delta ZXO},$$

viz. the forces, divided by the diagonals along which they act, are proportional to the reciprocals of the products of the two pairs of triangles which stand on these diagonals respectively. The negative sign shows, what is obvious, that the forces must be, one of them a pull, the other a push.

5-2